IXA-4NSW4518
IXA-4NSW4533

Dust/ Splash-proof | Battery-less Absolute | Arm Length: 450 mm | Vertical Axis: 180/330 mm

Model Specification Items

IXA	–	4	NSW	45		–		–	T2
Series		Number of axes	Type	Arm length	Vertical stroke		Cable length		Applicable controller

Number of axes		Type		Arm length		Vertical stroke	
4	4 axes	NSW	Dust- and splash-proof specification, high-speed type	45	450mm	18	180mm
						33	330mm

Cable length	
N	Nil
5L	5m
10L	10m
□L	Specified length (1m increments)

Applicable controller	
T2	XSEL-RAX/SAX

CE RoHS

Horizontal | Vertical | Side | Celling

POINT Selection Notes

(1) Please refer to P51 for Notes 1 - 9.

(2) The maximum set value for acceleration/deceleration varies depending on the weight of the object being transported, the travel distance, and the location. Operating continuously at the maximum set value could cause an overload error. For continuous operation, either lower the acceleration/deceleration values or refer to the duty (guideline) and set a stop time after acceleration/deceleration.

(3) Do not directly splash jet on the bellows. Connect a Φ16 air tube at the bellows intake/ exhaust joint to release its tip into clean air.

(4) A continuous operation cannot be performed for SCARA robots at 100% of speed and acceleration. Refer to the "Acceleration/Deceleration Setting Guidelines" for executable operating conditions.

Option

Name	Model number	Reference page
Flange	**IX-FL-1**	53
Metal cap for user wiring	**IXA-MC-1**	53

(Note) Please purchase separately.

Cable length

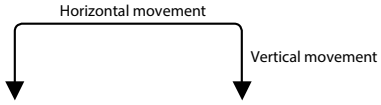
Type	Cable code	4-axis specification
Standard type	**5L**(5m)	○
	10L(10m)	○
Specified length	**1L**(1m) ~ **4L**(4m)	○
	6L(6m) ~ **9L**(9m)	○
	11L(11m)	○
	12L(12m)	○
	13L(13m)	○
	14L(14m)	○
	15L(15m)	○

(Note) Total amount of the following cables:
Motor cables:4, Encoder cables: 4, Brake cable: 1

Cycle time

Item	Time
Standard cycle time	0.38 seconds
Continuous cycle time	0.55 seconds

The standard/continuous cycle time represents the time required when an operation is performed with a cycle operation setting at maximum speed, under the following conditions.
2kg transport, vertical movement 25mm, horizontal movement 300mm (rough positioning arch motion)
[Standard cycle time]
The time required for maximum speed. This is a general guideline for high speed performance. Note that continuous operation is not possible under maximum speed operation.
[Continuous cycle time]
The cycle time for continuous operation.



Main specifications

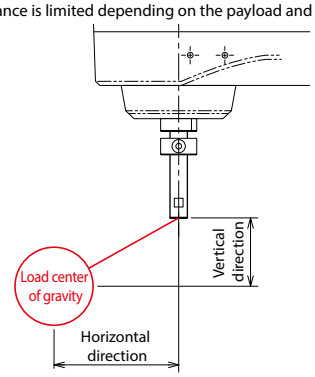
Item			Description
			4-axis specification
Max. payload (kg) (Note 1)			8
Speed (Note 2)	Combined max. speed (mm/s)		6981
	Max. speed of individual axes	1st arm (deg/s)	500
		2nd arm (deg/s)	700
		Vertical axis (mm/s)	1600
		Rotational axis (deg/s)	2000
Push force (N) (Note 3)		Upper limit	110
		Lower limit	25
Arm length (mm)			450
Individual arm length (mm)		1st arm	200
		2nd arm	250
Operation range of individual axes		1st arm (deg)	±137
		2nd arm (deg)	±133
		Vertical axis (mm)	180/330
		Rotational axis (deg)	±360

Item		Description
		4-axis specification
Positioning repeatability (Note 4)	Within horizontal surface	±0.01mm
	Vertical axis	±0.01mm
	Rotational axis	±0.005 degrees
User wiring		10-core (9-core + shield) AWG24 (rated 30V/Max. 1A)
User piping		Outer diameter Φ6, inner diameter Φ4, air tube 3 pcs. (max. usable pressure 0.6MPa)
Alarm lamp (Note 5)		Nil
Brake release switch (Note 6)		Brake release switch for preventing vertical axis from dropping.
Tip axis	Allowable torque	3.2 N·m
	Allowable load moment	9.6 N·m
Material of main parts		Refer to P61
Ambient operational temperature and humidity		0-40℃, 20-85% RH or lower (non-condensing)
Degree of protection		IP65 (except for bellows)
Air purge pressure (Note 8)		35kPa
Vibration- and impact-resistance		No impact or vibration should be applied.
Noise (Note 7)		80 dB or lower
International standard		CE marking, RoHS
Motor type		AC servo motor
Motor wattage	1st arm	600W
	2nd arm	400W
	Vertical axis	200W
	Rotational axis	100W
Encoder type		Battery-less absolute
Encoder pulse		16384 pulse/rev

Tip shaft allowable load inertia moment

Number of axes	Tip shaft allowable load inertia moment
4-axis specification	0.12 kg・m^2

Make sure that the offset value from the spline tip to the horizontal and vertical direction dimensions is within the guideline values listed below. A large load offset may cause abnormal noise, vibration, failure and shorter life time. Adjust the speed, acceleration/deceleration or center of gravity. The overhang distance is limited depending on the payload and operating condition.



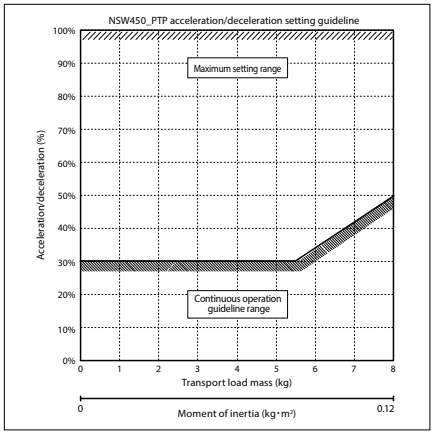
Horizontal direction	Vertical direction
120mm or less	100mm or less

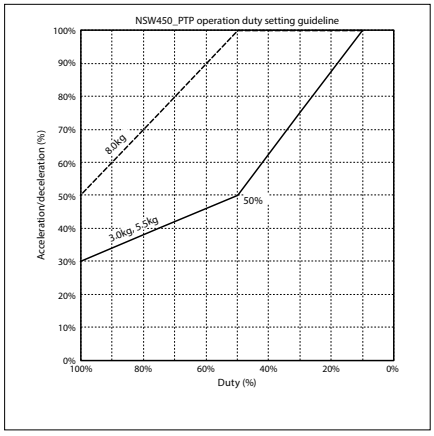
Acceleration/Deceleration Setting Guidelines

The SCARA Robot IXA cannot operate continuously at the maximum acceleration/deceleration or maximum speed specified in the catalog. To operate at the maximum acceleration/deceleration, set a stop time referring to the continuous operation duty guideline graph. If a continuous operation is required, do so within the continuous operation guideline range shown in the acceleration/deceleration setting guideline graph.

1) For a PTP operation, always use the WGHT command in the program to set the weight and moment of inertia. For the SCARA robot, the maximum acceleration/deceleration for each payload is set at 100%. When the payload differs, the operation time will also vary even at the same acceleration/deceleration or speed setting.
2) Adjust the acceleration/deceleration setting value by gradually increasing it from the continuous operation reference value.
3) If an overload error occurs, lower the acceleration/deceleration as required, or set a stop time by referring to the continuous operation duty guideline.
4) Duty (%) = (Operation time / (Operation time + Stop time)) x 100
5) When moving the robot horizontally at high speed, operate the vertical axis as close to the upward end as possible.
6) Set the moment of inertia and payload to the allowable value or lower.
7) The load mass represents the moment of inertia and weight at the center of rotation of the 4th axis.
8) Operate the robot at an appropriate acceleration/deceleration according to the weight and moment of inertia for the 4-axis specification. Otherwise, the drive section may become prematurely unusable or damaged, or vibration may occur.
9) If the load moment of inertia is high, vibration may occur in the vertical axis, depending on the position of the vertical axis. In such a case, decrease the acceleration/deceleration for operation as required.

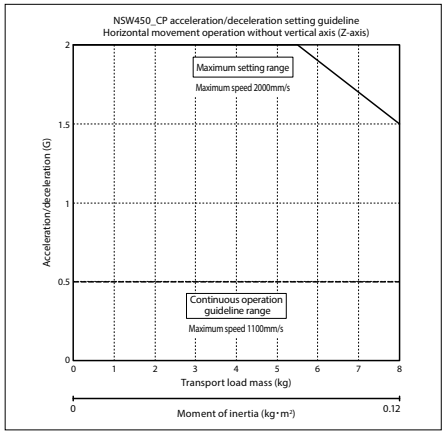
■PTP Operation



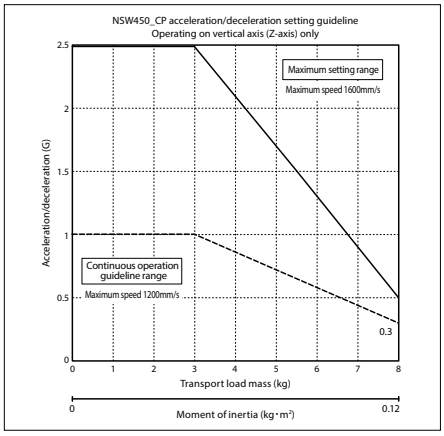


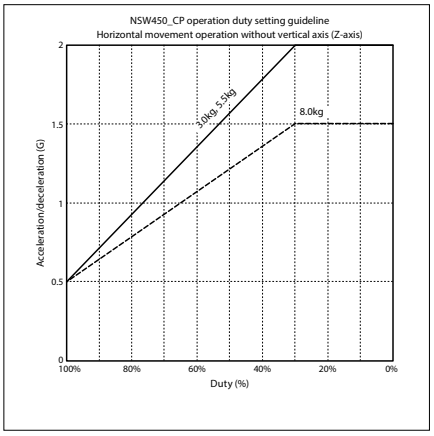
■CP Operation

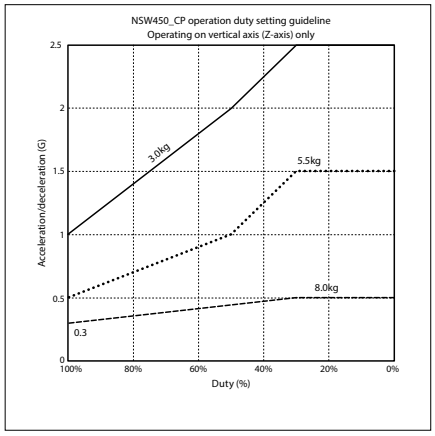
Horizontal



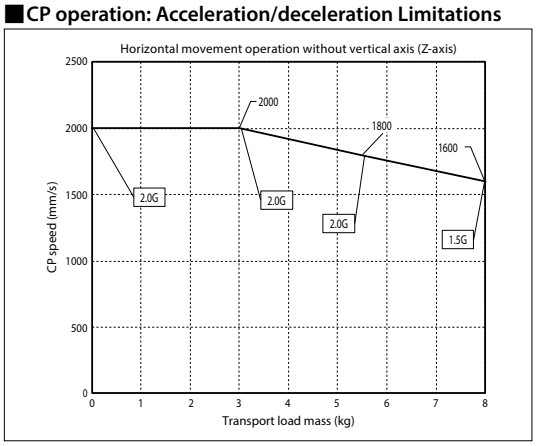
Vertical

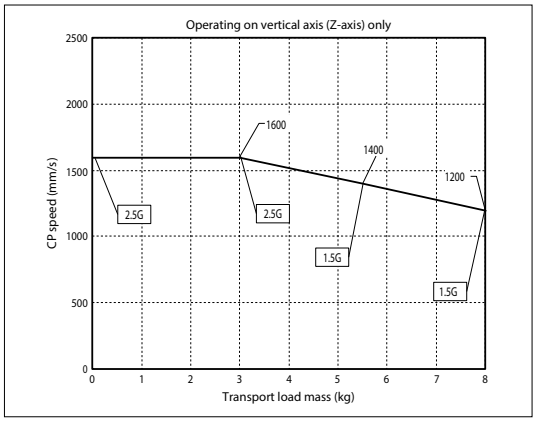






■CP operation: Acceleration/deceleration Limitations





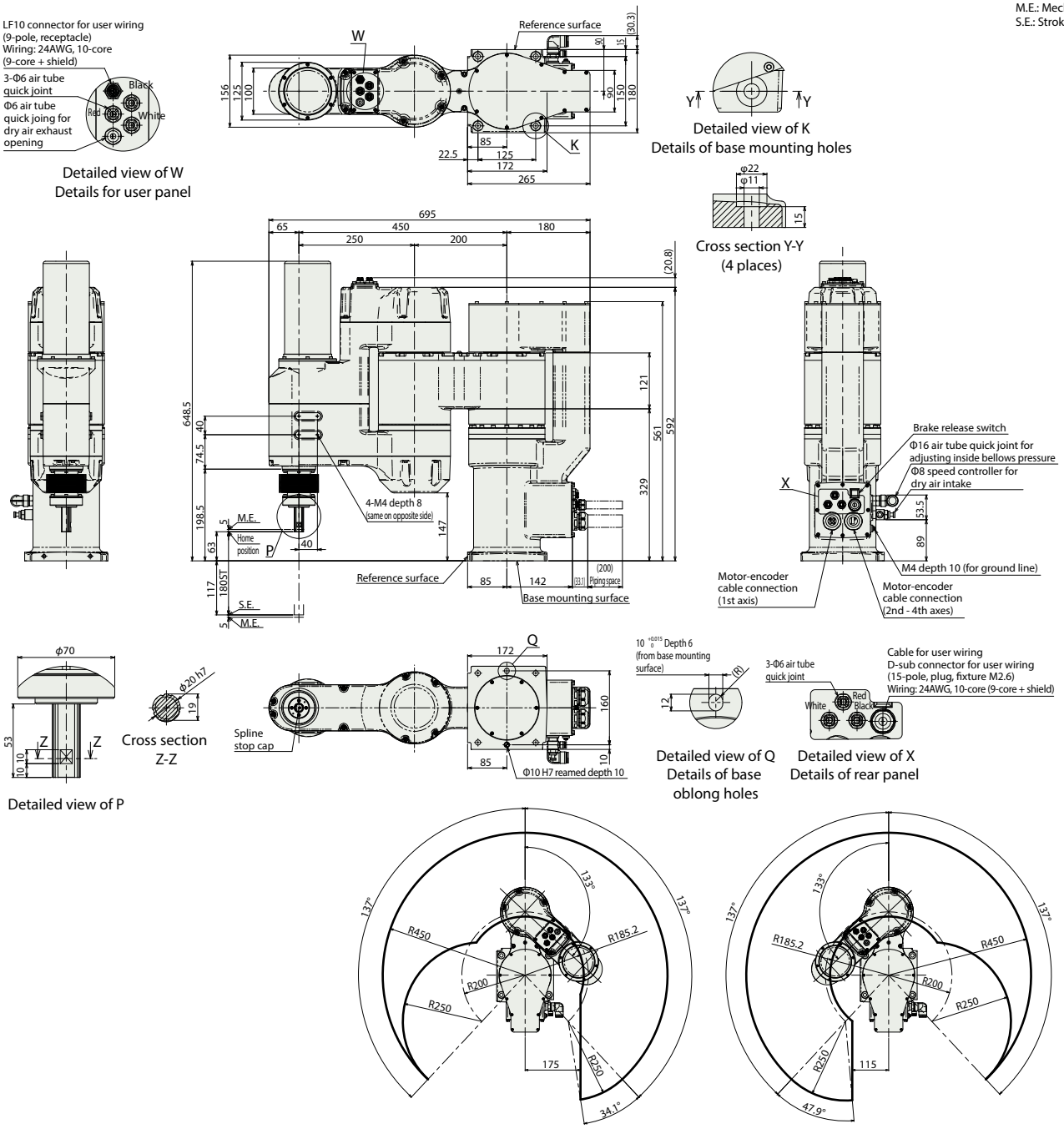
Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.com

S.T.: Stroke
M.E.: Mechanical end
S.E.: Stroke end

IXA-4NSW4518

(Note) Refer to P51 (Note 9) for cable connections



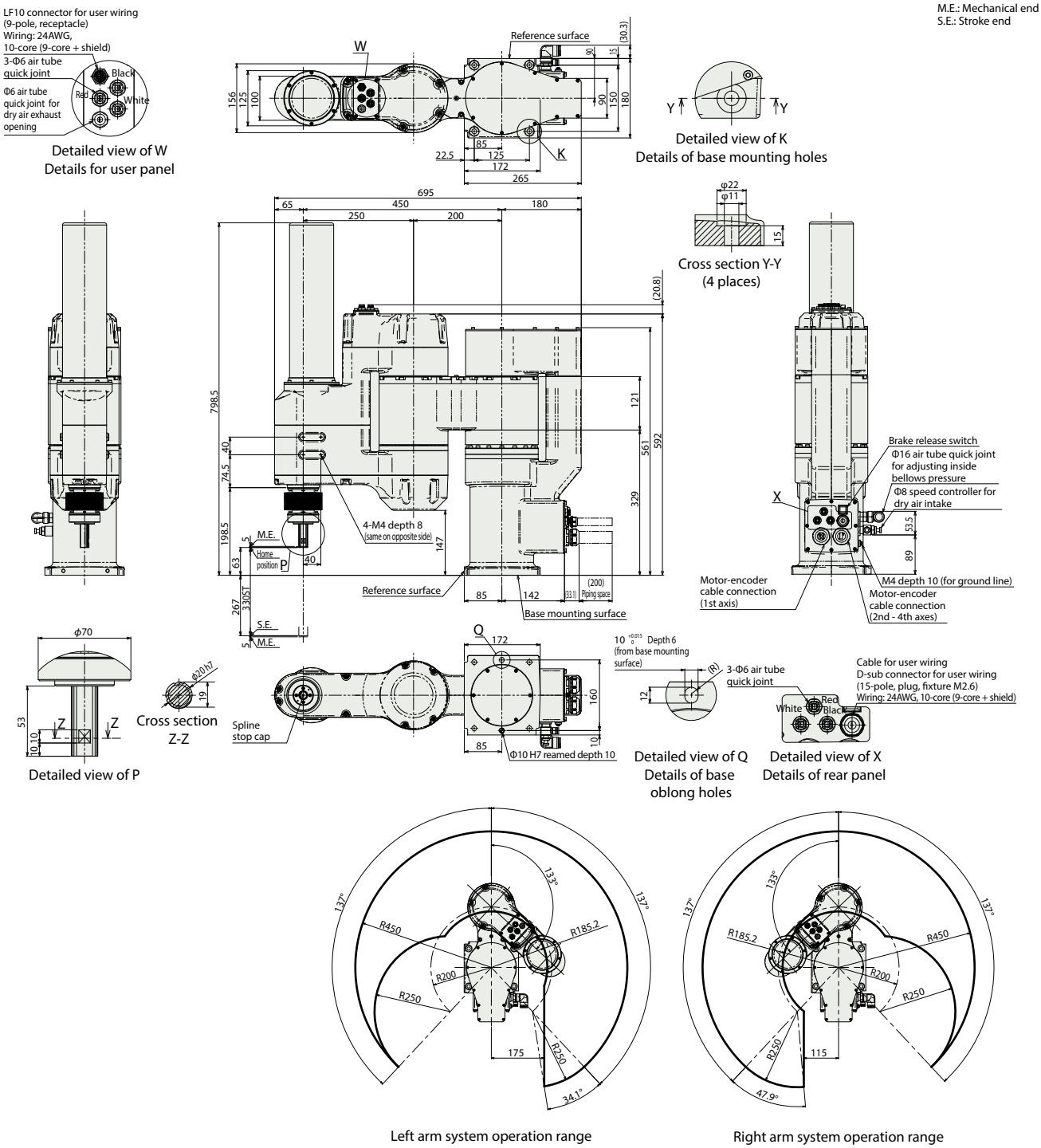
Mass

Item		Description
Mass	4-axis specification	52.0kg

IXA-4NSW4533

(Note) Refer to P51 (Note 9) for cable connections

S.T.: Stroke
M.E.: Mechanical end
S.E.: Stroke end



Left arm system operation range

Right arm system operation range

Mass

Item		Description
Mass	4-axis specification	53.0kg

Applicable controller

The actuator on this page can be operated by the controller indicated below.

Name	External view	Max. number of connectable axes	Power supply voltage	Control method														Max. number of positioning points	Reference page
				Positioner	Pulse train	Program	Network* option												
							DV	CC	CIE	PR	CN	ML	ML3	EC	EP	PRT	SSN	ECM	
XSEL-RAX4/SAX4 (for IX and IXA)		4	3-phase AC200V	—	—	●	●	●	—	●	—	—	—	●	●	—	—	—	36666 (Depending on the type)	54