IXA-3NNN3015
IXA-4NNN3015

Battery-less Absolute | Arm Length: 300 mm | Vertical Axis: 150 mm

Model Specification Items

IXA	–		NNN	30	15	–		–	T2	–	
Series	–	Number of axes	Type	Arm length	Vertical stroke	–	Cable length	–	Applicable controller	–	Option

Number of axes	
3	3 axes
4	4 axes

Type	
NNN	Standard type

Arm length	
30	300mm

Vertical stroke	
15	150mm

Cable length	
N	Nil
5L	5m
10L	10m
□L	Specified length (1m increments)

Applicable controller	
T2	XSEL-RAX/SAX

Option
See below

CE RoHS

Horizontal | Vertical | Side | Celling

POINT Selection Notes

(1) Please refer to P51 for Notes 1 - 9.

(2) The maximum set value for acceleration/deceleration varies depending on the weight of the object being transported, the travel distance, and the location. Operating continuously at the maximum set value could cause an overload error. For continuous operation, either lower the acceleration/deceleration values or refer to the duty (guideline) and set a stop time after acceleration/deceleration.

(3) If the motor is replaced, absolute reset must be performed. An adjustment jig will be required to perform an absolute reset on the rotational axis (4th axis). Please refer to P53 for details.

(4) A continuous operation cannot be performed for SCARA robots at 100% of speed and acceleration. Refer to the "Acceleration/Deceleration Setting Guidelines" for executable operating conditions.

Option

Name	Model number	Reference page
LED pilot lamp	**LED**	53

Option

Name	Model number	Reference page
Flange	**IX-FL-1**	53

(Note) Please purchase separately.

Cable length

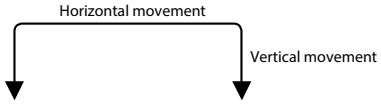
Type	Cable code	3-axis specification	4-axis specification
Standard type	**5L**(5m)	○	○
	10L(10m)	○	○
Specified length	**1L**(1m) ~ **4L**(4m)	○	○
	6L(6m) ~ **9L**(9m)	○	○
	11L(11m)	○	○
	12L(12m)	○	○
	13L(13m)	○	○
	14L(14m)	○	○
	15L(15m)	○	○

(Note) Total amount of the following cables:
[3-axis spec.] Motor cables:3, Encoder cables: 3, Brake cable: 1
[4-axis spec.] Motor cables:4, Encoder cables: 4, Brake cable: 1

Cycle time

Item	Time
Standard cycle time	0.38 seconds
Continuous cycle time	0.55 seconds

The standard/continuous cycle time represents the time required when an operation is performed with a cycle operation setting at maximum speed, under the following conditions.
2kg transport, vertical movement 25mm, horizontal movement 300mm (rough positioning arch motion)
[Standard cycle time]
The time required for maximum speed. This is a general guideline for high speed performance. Note that continuous operation is not possible under maximum speed operation.
[Continuous cycle time]
The cycle time for continuous operation.



Main specifications

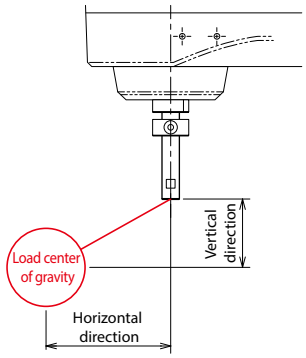
Item			Description	
			3-axis specification	4-axis specification
Max. payload (kg) (Note 1)			3	
Speed (Note 2)	Combined max. speed (mm/s)		5529	
	Max. speed of individual axes	1st arm (deg/s)	660	
		2nd arm (deg/s)	660	
		Vertical axis (mm/s)	1400	
		Rotational axis (deg/s)	—	1600
Push force (N) (Note 3)		Upper limit	60	
		Lower limit	10	
Arm length (mm)			300	
Individual arm length (mm)		1st arm	120	
		2nd arm	180	
Operation range of individual axes		1st arm (deg)	±135	
		2nd arm (deg)	±142	
		Vertical axis (mm)	150	
		Rotational axis (deg)	—	±360

Item		Description	
		3-axis specification	4-axis specification
Positioning repeatability (Note 4)	Within horizontal surface	±0.01mm	
	Vertical axis	±0.01mm	
	Rotational axis	—	±0.005 degrees
User wiring		10-core (9-core + shield) AWG24 (rated 30V/Max. 1A)	
User piping		Outer diameter Φ4, inner diameter Φ2.5, air tube 3 pcs. (max. usable pressure 0.6MPa)	
Alarm lamp (Note 5)		Amber color LED, small pilot lamp 1 pc. (DC24V supply required)	
Brake release switch (Note 6)		Brake release switch for preventing vertical axis from dropping.	
Tip axis	Allowable torque	3.2 N·m	3.2 N·m
	Allowable load moment	4.5 N·m	
Ambient operational temperature and humidity		0-40℃, 20-85% RH or lower (non-condensing)	
Degree of protection		IP20	
Vibration- and impact-resistance		No impact or vibration should be applied.	
Noise (Note 7)		80 dB or lower	
International standard		CE marking, RoHS	
Motor type		AC servo motor	
Motor wattage	1st arm	400W	
	2nd arm	200W	
	Vertical axis	100W	
	Rotational axis	—	100W
Encoder type		Battery-less absolute	
Encoder pulse		16384 pulse/rev	

Tip shaft allowable load inertia moment

Number of axes	Tip shaft allowable load inertia moment
3-axis specification	0.06 kg・m²
4-axis specification	

The 4th axis allowable inertia moment is the allowable inertial moment value for the center of rotation conversion of the 4th axis (rotational axis) of the SACRA robot. Make sure that the offset value from center of the rotation of the 4th axis to the tool center of gravity is within the guideline values listed below. If the tool center of gravity is far from the 4th axis center, it is necessary to reduced speed and acceleration/deceleration appropriately. The overhang distance is limited depending on the payload and operating condition.



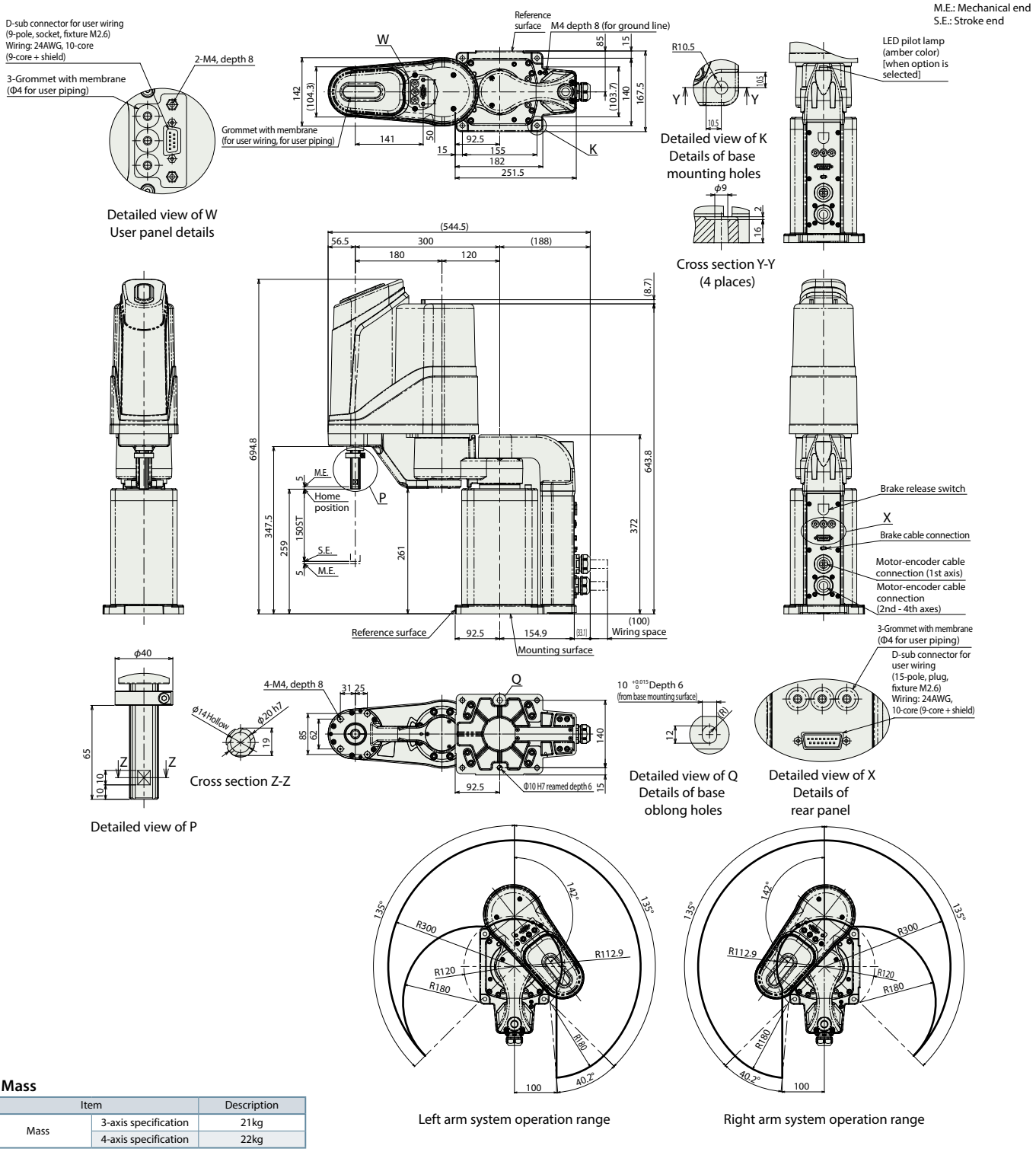
Horizontal direction	Vertical direction
150mm or less	100mm or less

Dimensions

CAD drawings can be downloaded from our website.
www.intelligentactuator.com
2D CAD 3D CAD

(Note) Refer to P51 (Note 9) for cable connections

S.T.: Stroke
M.E.: Mechanical end
S.E.: Stroke end



Mass

Item		Description
Mass	3-axis specification	21kg
	4-axis specification	22kg

Applicable controller

The actuator on this page can be operated by the controller indicated below.

Name	External view	Max. number of connectable axes	Power supply voltage	Control method															Max. number of positioning points	Reference page
				Positioner	Pulse train	Program	Network* option													
							DV	CC	CIE	PR	CN	ML	ML3	EC	EP	PRT	SSN	ECM		
XSEL-RAX/SAX		8	3-phase AC200V	—	—	●	●	●	—	●	—	—	—	●	●	—	—	—	36666 (Depending on the type)	54

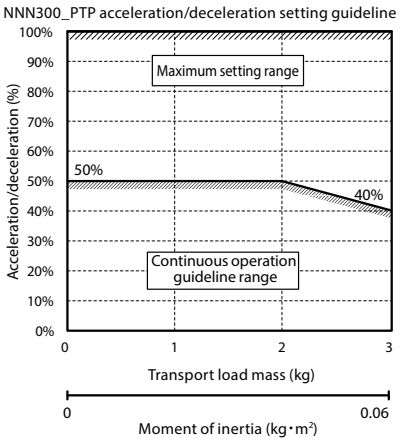
(Note) Up to one SCARA robot + one 4-axis robot can be controlled.

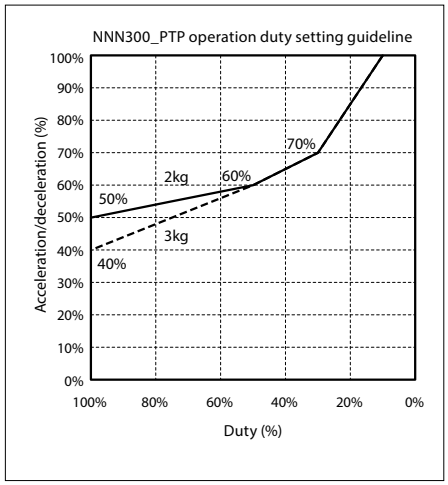
Acceleration/Deceleration Setting Guidelines

The SCARA Robot IXA cannot operate continuously at the maximum acceleration/deceleration or maximum speed specified in the catalog. To operate at the maximum acceleration/deceleration, set a stop time referring to the continuous operation duty guideline graph. If a continuous operation is required, do so within the continuous operation guideline range shown in the acceleration/deceleration setting guideline graph.

1) For a PTP operation, always use the WGHT command in the program to set the weight and moment of inertia. For the SCARA robot, the maximum acceleration/deceleration for each payload is set at 100%. When the payload differs, the operation time will also vary even at the same acceleration/deceleration or speed setting.
2) Adjust the acceleration/deceleration setting value by gradually increasing it from the continuous operation reference value.
3) If an overload error occurs, lower the acceleration/deceleration as required, or set a stop time by referring to the continuous operation duty guideline.
4) Duty (%) = (Operation time / (Operation time + Stop time)) x 100
5) When moving the robot horizontally at high speed, operate the vertical axis as close to the upward end as possible.
6) Set the moment of inertia and payload to the allowable value or lower.
7) The load mass represents the moment of inertia and weight at the center of rotation of the 4th axis.
8) Operate the robot at an appropriate acceleration/deceleration according to the weight and moment of inertia for the 4-axis specification. Otherwise, the drive section may become prematurely unusable or damaged, or vibration may occur.
9) If the load moment of inertia is high, vibration may occur in the vertical axis, depending on the position of the vertical axis. In such a case, decrease the acceleration/deceleration for operation as required.

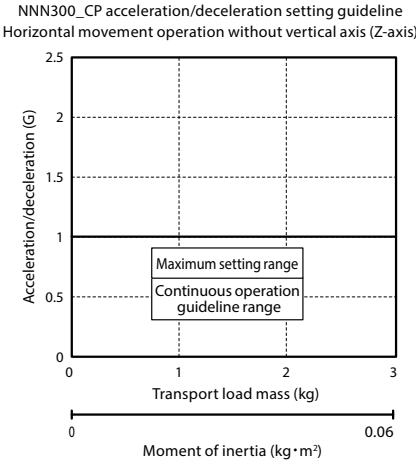
■PTP Operation



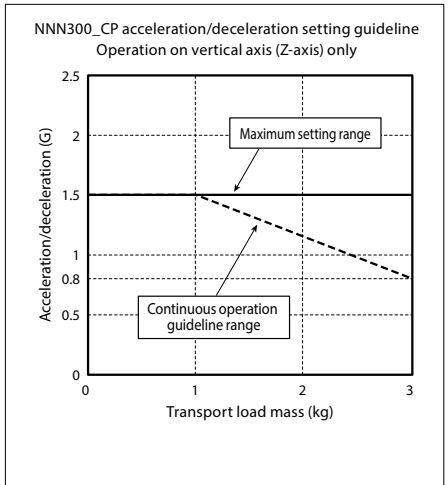


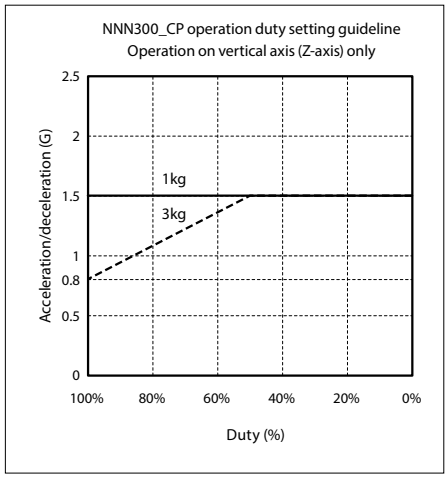
■CP Operation

Horizontal



Vertical





■CP operation: Acceleration/deceleration Limitations