

## Model/Specification

0.5

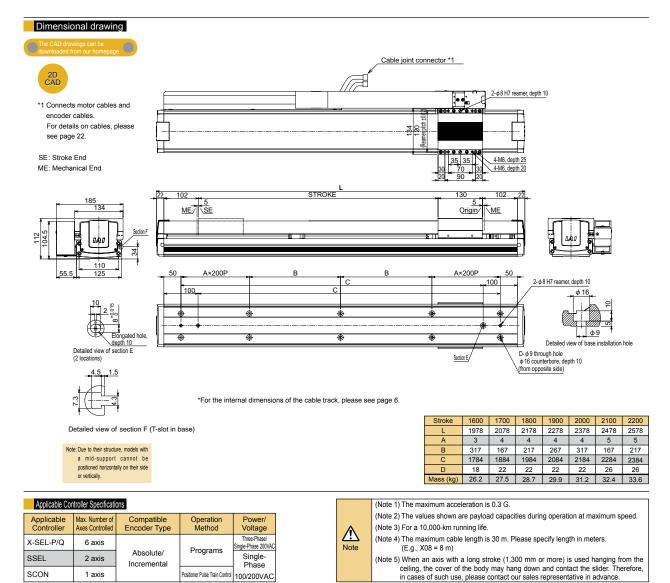
Model	Encoder Type	Motor Output (W)	Lead (mm)	Stroke (mm)	I (mm/s)	Acceleration (Note 1)		Payload capacity (Note 1 & 2)		
						Horizontal (G)	Vertical (G)	Horizontal (kg)	Vertical (kg)	Rated Thrust (N)
						Rated Maximum	Rated Maximum	Rated Maximum Acceleration Acceleration	Rated Maximum Acceleration Acceleration	(,
NS-MXMXS-10-200-30-12-10-AQ-10-RT	Absolute	200	30	1600~2200	1800	0.3	Horizontal Only	25	Horizontal Only	113.9
	Incremental		20		1200	0.3		40		170.9

\*In the model above, 🕥 indicates the type of encoder, 应 indicates the stroke, 💿 indicates the cable length, and 🕢 indicates the option.

Option			
Name	Model	Reference page	Note
AQ Seal	AQ	→P5	Standard Equipment
Installation Direction of Standard Cable Track	CT1~CT4	→P5	Enter CT1 for standard installation
Guide with Ball-Retaining Mechanism	RT	→P6	Standard Equipment

## Common specifications

Driving Method	Ball Thread, Diameter
Repeated Positioning Accuracy	+/- 0.01 mm
Backlash	0.02 mm or less
Guide	Integrated to Base
Dynamic Allowable Moment (Note 3)	Ma: 69.6N·m, Mb: 99.0N·m, Mc: 161.7N·m
Overhung load length	Ma Direction: 600mm or less; Mb and Mc Direction: 600mm or less
Base	Material: Aluminium, White Alumite Treatment
Cable Length (Note 4)	N: No cable; S: 3 m; M: 5 m; X II: Length specified
Ambient Temperature	0~40 degrees Celsius, 85% RH or less (No condensation)



SCON

1 axis

Positioner Pulse Train Control

100/200VAC